SmartX Actuators - Electric Dampers
Non-Spring Return Rotary
24 Vac - Floating Control
General Instructions

## Description

These direct coupled 24 Vac Non-Spring Return rotary electric SmartX Actuators are designed for threeposition (floating) control of dampers.

## Features

- Compact, lightweight design
- Manual override
- $5^{\circ}$ preload as shipped from factory
- Plenum cabling
- Feedback potentiometer models available
- cUL and UL listed; plenum versions also CE certified
- Independently adjustable dual auxiliary switches available


## Applications



These actuators are used in constant or variable air volume installations for control of HVAC dampers requiring up to 44 lb -in $(5 \mathrm{Nm})$ torque or 88 lb -in $(10 \mathrm{Nm})$.

## Product Numbers

| Torque | 24 Vac Operating Voltage |  |  |
| :---: | :---: | :---: | :---: |
|  |  | Standard | Feedback Potentiometer <br> $1 K$ |
|  |  |  | - |
| $44 \mathrm{lb}-$ in $(5 \mathrm{Nm})$ | Plenum | MF41-6043 | - |
| $88 \mathrm{lb}-\mathrm{in}(10 \mathrm{Nm})$ | Plenum | MF41-6083 | MF41-6083-510 |



Precautions

[^0][^1]| Specifications | Operating voltage (G-Y1 or G-Y2): Frequency: | $\begin{aligned} & 24 \mathrm{Vac}+20 \%,-15 \% \\ & 50 / 60 \mathrm{~Hz} \end{aligned}$ |
| :---: | :---: | :---: |
| Power Supply | Power consumption: | 2.3 VA |
| Auxiliary Features | Feedback potentiometer: | 0 to $1000 \Omega$ |
|  | (MF41-6083-510) | <10 mA |
|  | Dual auxiliary switch contact rating: |  |
|  | AC rating | 24 Vac |
|  | DC rating | 4 A resistive, 2 A inductive DC 2A |
|  | Switch Range |  |
|  | Switch A | $0^{\circ}$ to $90^{\circ}$ with $5^{\circ}$ intervals |
|  | Recommended range usage | $0^{\circ}$ to $45^{\circ}$ |
|  | Factory setting | $5^{\circ}$ |
|  | Switch B | $0^{\circ}$ to $90^{\circ}$ with $5^{\circ}$ intervals |
|  | Recommended range usage | $45^{\circ}$ to $90^{\circ}$ |
|  | Factory setting | $85^{\circ}$ |
|  | Switching hysteresis | $2^{\circ}$ |
| Function | Torque: |  |
|  | MF41-6043 | $44 \mathrm{lb}-\mathrm{in}(5 \mathrm{Nm})$ |
|  | MF41-6083 Series | 88 lb -in (10 Nm) |
|  | Runtime for $90^{\circ}$ opening or closing: |  |
|  | MF41-6043 | 90 seconds. at 60 Hz |
|  |  | ( 108 seconds at 50 Hz ) |
|  | MF41-6083 Series | 125 seconds at 60 Hz |
|  |  | ( 150 seconds at 50 Hz ) |
|  | Nominal angle of rotation | $90^{\circ}$ |
|  | Maximum angular rotation | $95^{\circ}$ |
| Mounting | Shaft size: | Minimum shaft length 3/4-inch ( 20 mm ) |
| Housing | Enclosure | NEMA Type 2 |
|  |  | IP54 according to EN60529 |
|  | Material | Durable plastic |
|  | Gear lubrication | Silicone-free |
| Ambient | Ambient temperature: |  |
| Conditions | Operation | $-25^{\circ} \mathrm{F}$ to $130^{\circ} \mathrm{F}\left(-32^{\circ} \mathrm{C}\right.$ to $\left.55^{\circ} \mathrm{C}\right)$ |
|  | Storage and transport | $-40^{\circ} \mathrm{F}$ to $158^{\circ} \mathrm{F}\left(-40^{\circ} \mathrm{C}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
|  | Voltage Requirements for 6083 |  |
|  | Series at High Temperatures: |  |
|  | Minimum Voltage: | $24 \mathrm{Vac}+20 \%$, -10\% |
|  |  | $90^{\circ} \mathrm{F}$ to $130^{\circ} \mathrm{F}\left(32^{\circ} \mathrm{C}\right.$ to $\left.55^{\circ} \mathrm{C}\right)$ |
|  | Ambient humidity (non-condensing) | 95\% rh |

## Specifications (cont.)

## Agency Certification

UL 873
cUL certified to Canadian
Standard C22.2 No. 24-93

| CE Conformity |
| :--- |
|  |
| Miscellaneous |

Pre-cabled connection
Cable length
Life cycle
Dimensions
Weight

89/336/EEC
EN 61000-6-3:2001
EN 61000-6-2:2001
EN 60730-2-14:2001

18 AWG
3 feet ( 0.9 m )
Five-year warranty
See Figure 7
$1.06 \mathrm{lb}(0.48 \mathrm{~kg})$

## Actuator

## Components



Figure 1. Parts of the Actuator.

## Legend

1. Base plate
2. Positioning scale for angle of rotation
3. Connection cables
4. Connection cables
5. Manual override
6. Coupling bushing
7. $1 / 2$-inch guide
8. Auxiliary switch A
9. Auxiliary switch $B$
10. Position indicator
11. Adjustment lever with locking screw (4 mm hex)
12. Set screw for mechanical range stop (3 mm hex)
13. Anti-rotation bracket

A floating control signal controls the damper actuator. The actuator's angle of rotation is proportional to the length of time the signal is applied. A 24 Vac control signal to wires 1 and 6 (G-Y1) causes the actuator coupling to rotate clockwise. A 24 Vac control signal to wires 1 and 7 (G-Y2) causes the actuator coupling to rotate counterclockwise.
To reverse the direction of rotation, the wires 6 and 7 ( Y 1 and Y 2 ) can be interchanged.
In the event of a power failure or with no control voltage, the damper actuator holds its position.

## Life

expectancy
Dual Auxiliary
Switch

## Sizing

An improperly tuned loop will cause excessive repositioning that will shorten the life of the actuator.

Figure 2 shows the adjustable switching values for the auxiliary switches $A$ and $B$.
Actuator Scale: clockwise

Adjustment range for
Switches A and B
Setting interval: $5^{\circ}$
Switching hysteresis: $2^{\circ}$
Actuator Scale:
counterclockwise


Figure 2. Adjustable Switching Values for the dual auxiliary Switches.

## Notes:

- The auxiliary switch setting shafts rotate with the actuator. The scale is valid only when the actuator is in the " 0 " position on clockwise motion.
- For the counterclockwise rotation, the adjustment lever has to move from $90^{\circ}$ to $0^{\circ}$ by using the manual override and then adjust the auxiliary switches. After the auxiliary switches are adjusted, the adjustment lever has to move back to the $90^{\circ}$ position.
- Use the long arm of the $X$ to point to the position of switch A. Use the narrower tab on the red ring to point to the position of switch B.

The type of actuator required depends on several factors.

1. Obtain damper torque ratings ( $\mathrm{ft}-\mathrm{lb} / \mathrm{ft} 2$ or $\mathrm{Nm} / \mathrm{m} 2$ ) from the damper manufacturer.
2. Determine the area of the damper.
3. Calculate the total torque required to move the damper:

$$
\text { Total Torque }=\frac{\text { Torque Rating } \times \text { Damper Area }}{\mathrm{SF}^{1}}
$$

${ }^{1}$ Safety Factor: When determining the torque of an actuator required, a safety factor should be included for unaccountable variables such as slight misalignments, aging of the damper, etc. A suggested safety factor is 0.80 (or $80 \%$ of the rated torque).
4. Select the actuator type from the table below:

| Total Torque | Actuator |
| :---: | :---: |
| $44 \mathrm{lb}-\mathrm{in}(5 \mathrm{Nm})$ | MF41-6043 |
| $88 \mathrm{lb}-\mathrm{in}(10 \mathrm{Nm})$ | MF41-6083 Series |

You must place the actuator on the damper shaft so that the front of the actuator is accessible. The label is the front side. The minimum damper drive shaft length is $3 / 4$-inch ( 20 mm ).


Note: For all damper shafts with the exception of the 1/2-inch round shaft: Remove 1/2inch diameter guide before installation

Figure 3. Damper Shaft Sizes.

- An anti-rotation bracket is included with the actuator.
- Observe the service envelope around the actuator as shown in Figure 7.
- For detailed mounting instructions, see Installation Instructions F-27211.


## Manual <br> override

To move the damper blades and lock the position with no power present:

1. Slide the red manual override knob toward the back of the actuator.
2. Make adjustments to the damper position.
3. Slide the red manual override knob toward the front of the actuator.

Once power is restored, the actuator returns to automated control.


Figure 4. Manual Override.

## Mechanical range adjustment

To mechanically limit the range of the damper blade.

1. Loosen the stop set screw.
2. Move the screw along the track to the desired position, and fasten it in place.


Figure 5. Moving the Mechanical Range Stop.

All wiring must conform to NEC and local codes and regulations. Use earth ground isolating step-down Class 2 transformers.
Do not use autotransformers.
The sum of the VA ratings of all actuators and all other components powered by one transformer must not exceed the rating of the transformer. It is recommended that one transformer power no more than 10 actuators.

Caution: Do not wire different types of actuators (such as MS/MF41-6153 Series) in parallel with these models.

Warning: All six outputs of the dual auxiliary switch (A and B) must only be connected to: Class 2 voltage (UL/C-UL).
Separated Extra-Low Voltage (SELV) or Protective Extra Low Voltage (PELV) (according to HD384 441) for installations requiring CE conformance. You must use a CE certified plenum actuator.

Warning: Installations requiring CE Conformance:

- All wiring for CE certified actuators must only be separated extra low voltage (SELV) or protective extra low voltage (PELV) per HD384-4-41.
- Use safety-isolating transformers (Class III transformer) per EN61558. They must be rated for 100\% duty cycle.
- Overcurrent protection for supply lines is maximum 10A.


## Direction of damper rotation

To reverse the direction of rotation, wires 6 (violet) and 7 (orange) can be interchanged.
Wire
Designations
Each wire has the standard symbol printed on it.


Figure 6. Three-position Control.

Wire Designations Continued

## 24 Vac power supply Three-position control 24 Vac



Three-position Control 24 Vac.

## Start-Up/

Commissioning
Check that the wires are connected correctly. Connect wires 1 (red) and 6 (violet) to a Digital Multimeter (DMM) with the dial set at Vac. Apply a control signal ( 24 Vac ) to wires 1 and 6 to verify that the operating voltage is within range. Connect wires 1 (red) and 7 (orange) to a DMM with the dial set at Vac. Apply a control signal (24 Vac) to wires 1 and 7 to verify that the operating voltage is within range.

1. Check operation:
a. Connect wire 1 (red) to the actuator.
b. Apply a control signal ( 24 Vac ) to wires 1 (red) and 6 (violet).
c. Allow the actuator shaft coupling to rotate from $0^{\circ}$ to $90^{\circ}$.
d. Stop applying a control signal to wires 1 (red) and 6 (violet).
e. Apply a control signal ( 24 Vac ) to wires 1 (red) and 7 (orange).
f. Allow the actuator shaft coupling to rotate from $90^{\circ}$ to $0^{\circ}$.
2. Check Feedback:
a. Set the DMM dial to ohms.
b. Connect wires P1 and P2 to the DMM. The DMM should indicate a resistive value.
c. Apply a control signal $(24 \mathrm{Vac})$ to wires 1 (red) and 6 (violet). The reading of the DMM should increase.
d. Connect wires P 2 and P 3 to the DMM . The DMM should indicate a resistive value.
e. Apply a control signal ( 24 Vac ) to wires 1 (red) and 7 (orange). The reading of the DMM should increase.
3. Check Auxiliary Switch A:
a. Set the DMM dial to ohms (resistance) or continuity check.
b. Connect wires S1 and S3 to the DMM. The DMM should indicate an open circuit or no resistance.
c. Apply a control signal ( 24 Vac ) to wires 1 (red) and 6 (violet). The DMM should indicate contact closure as the actuator shaft coupling reaches the setting of switch $A$.
d. Stop applying a control signal to wires 1 (red) and 6 (violet).
e. Connect wires S1 and S2 to the DMM. The DMM should indicate an open circuit or no resistance.
f. Apply a control signal ( 24 Vac ) to wires 1 (red) and 7 (orange).
g. The DMM should indicate contact closure as the actuator shaft coupling reaches the setting of switch A.
a. Set the DMM dial to ohms (resistance) or continuity check.
b. Connect wires S4 and S6 to the DMM. The DMM should indicate an open circuit or no resistance.
c. Apply a control signal ( 24 Vac ) to wires 1 (red) and 6 (violet). The DMM should indicate contact closure as the actuator shaft coupling reaches the setting of switch B.
d. Stop applying a control signal to wires 1 (red) and 6 (violet).
e. Connect wires S4 and S5 to the DMM. The DMM should indicate an open circuit or no resistance.
f. Apply a control signal ( 24 Vac ) to wires 1 (red) and 7 (orange) The DMM should indicate contact closure as the actuator shaft coupling reaches the setting of switch B.

## Service

Warning: Do not open the actuator. If the actuator is inoperative, replace the unit.

## Dimensions



Figure 7. Dimensions of the SmartX Actuator and Anti-rotation Bracket.


[^0]:    Warning: Personal injury or loss of life may occur if you do not follow a procedure as specified.

[^1]:    Caution: Equipment damage or loss of data may occur if you do not follow a procedure as specified.

