B2...HT... Two-way High Temperature Characterized Control Valve Stainless Steel Ball and Stem



Suitable Actuators

Spring Non-Spring







Application

Valve Nominal Size

Inches DN [mm] 2-way NPT

This valve is typically used in air handling units on heating or cooling coils, and fan coil unit heating or cooling coils. Some other common applications include Unit Ventilators, VAV box re-heat coils and bypass loops. This valve is suitable for use in a hydronic system with variable flow.

This valve is designed to fit in compact areas where on/off or floating point control is required using 24 VAC.

Type

water/low pressure steam, 60% glycol
A-port equal percentage
1/2", 3/4", 1"
female, NPT
brass (DZR) P-CuZn35Pb2
stainless steel
stainless steel
PTFE Teflon
PTFE Teflon
2 EPDM O-rings
600 psi
250°F (15 psig)
37°F - 266°F
200 psi
116 psi full open ball
60 psi partially open ball
bubble tight 0%

Dimensions		
	C C A A	HTCCV_DimAB

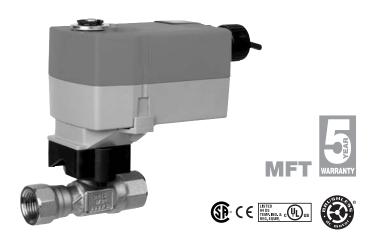
		Valve Nor	ninal Size	Dimen	sions (Inches	[mm])
	Valve Body	Inches	DN [mm]	Α	В	C
	B215HT	1/2"	15	3.33" [84.6]	2.09" [53.2]	0.53" [13.5]
	B220HT	3/4"	20	3.96" [100.6]	2.37" [60.1]	0.67" [17.0]
•	B225HT	1"	25	5.14" [130.6]	3.14" [79.8]	0.92" [23.25]

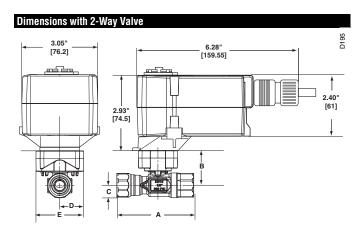
Flow Patterns	
A AB OUTLET Two-way Characterizing Disc (where applicable)	Flow direction

0.29	1/2	15	B215HT029	•			
0.46	1/2	15	B215HT046				
0.73	1/2	15	B215HT073			Series	
1.16	1/2	15	B215HT116	Series		Sei	
1.86	1/2	15	B215HT186	LE L		똩	
2.90	1/2	15	B215HT290				
4.55	1/2	15	B215HT455*				
1.86	3/4	20	B220HT186				
2.90	3/4	20	B220HT290				
4.64	3/4	20	B220HT464				
7.31	3/4	20	B220HT731				
9.28	3/4	20	B220HT928		Series		Series
13.20	3/4	20	B220HT1320		Ser		Ser
4.64	1	25	B225HT464		5		Ľ
7.31	1	25	B225HT731				
11.6	1	25	B225HT1160				
18.56	1	25	B225HT1856				
28.00	1	25	B225HT2800				
* modified	equal percent	age					

TF24-MFT US Actuators, Multi-Function Technology







Valve Nominal Size Dimensions (Inches [mm]) Valve Body Inches DN [mm] A B C B215HT ½" 15 3.33" [84.6] | 2.09" [53.2] | 0.53" [13.5]

Models

TF24-MFT US

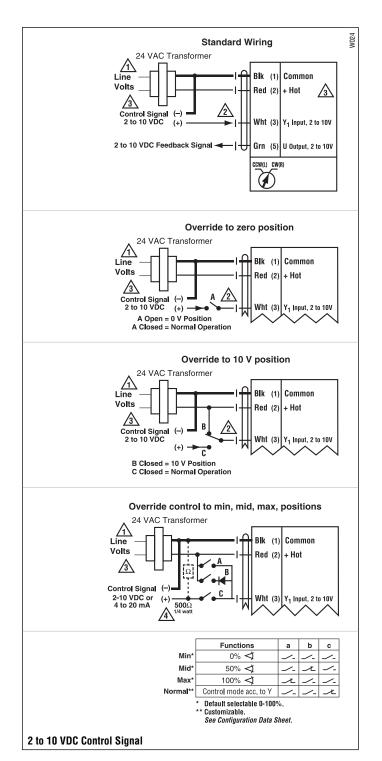
Technical Data Control MFT Power supply $24 \text{ VAC} \pm 20\% 50/60 \text{ Hz}$ $24 \text{ VDC} \pm 10\%$ Power consumption running 2.5 W holding 1.0 W Transformer sizing $4 \text{ VA (class 2 power source)}$ Electrical connection $3 \text{ ft, 18 GA plenum rated cable}$ $1000000000000000000000000000000000000$
Power supply $ \begin{array}{c} 24 \text{ VAC} \pm 20\% 50/60 \text{ Hz} \\ 24 \text{ VDC} \pm 10\% \\ \hline \\ Power consumption \\ holding \\ \hline \\ Transformer sizing \\ \hline \\ Electrical connection \\ \hline \\ Signature \\ \hline \\ Signature \\ \hline \\ Signature \\ \hline \\ Power consumption \\ holding \\ \hline \\ Transformer sizing \\ \hline \\ In UW \\ \hline \\ In UW \\ \hline \\ Signature \\ \hline \\ Power consumption \\ running g \\ holding \\ \hline \\ Signature $
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
Power consumption running holding
holding 1.0 W
Transformer sizing 4 VA (class 2 power source) Electrical connection 3 ft, 18 GA plenum rated cable ½" conduit connector Overload protection electronic throughout 0° to 95° rotation Operating range Y* 2 to 10 VDC 4 to 20 mA (w/500 Ω , ¼ W resistor) ZG-R01 Input impedance $100k \Omega$ for 2 to 10 VDC (0.1 mA) 500Ω for 4 to 20 mA 1500Ω for PWM, Floating point and On-Off control Feedback output U* 2 to 10 VDC, 0.5 mA max Direction of rotation spring reversible with CW/CCW mounting Mechanical angle of rotation* 95° Running time motor* Spring 95 ° sec constant independent of load < 25 sec @-4°F to 122 °F [< 20 °C to 50 °C] < 60 sec @- < 22 °F [< 30 °C] Angle of Rotation Adaptation* Off (Default) Override control* Min. (Min Position) = 0% < 10 Min. (Min Position) = 100% < 10 Min. (Min Position) = 100%
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$\begin{tabular}{lllllllllllllllllllllllllllllllllll$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
Operating range Y*
$\begin{array}{c} 4 \text{ to 20 mA} \\ (\text{w}/500 \ \Omega, 14 \text{ W resistor}) \text{ ZG-R01} \\ \hline \\ \text{Input impedance} \\ \hline \\ 100k \ \Omega \text{ for 2 to 10 VDC (0.1 mA)} \\ 500 \ \Omega \text{ for 4 to 20 mA} \\ 1500 \ \Omega \text{ for PWM, Floating point and} \\ \hline \\ \text{On-Off control} \\ \hline \\ \hline \\ \text{Eedback output U*} \\ \hline \\ \text{Direction of rotation} \\ \hline \\ \text{Spring} \\ \hline \\ \text{Running time} \\ \hline \\ \text{Motor*} \\ \hline \\ \text{Spring} \\ \hline \\ \text{Spring} \\ \hline \\ \text{Spring} \\ \hline \\ \text{Angle of Rotation Adaptation*} \\ \hline \\ \text{Override control*} \\ \hline \\ \text{Override control*} \\ \hline \\ \text{Min. (Min Position) = 0\%} \\ \hline \\ \text{- ZS (Mid. Position) = 100\%} \\ \hline \\ \text{- Max. (Max. Position) = 100\%} \\ \hline \end{array}$
Input impedance $\begin{array}{c} 100k\ \Omega\ \text{for 2 to 10 VDC (0.1 mA)} \\ 500\ \Omega\ \text{for 4 to 20 mA} \\ 1500\ \Omega\ \text{for PWM, Floating point and} \\ \hline 0n\text{-Off control} \\ \hline \\ Peedback\ \text{output U*} \\ \hline \\ Direction\ \text{of rotation} \\ \hline \\ \text{motor} \\ \hline \\ \text{Running time} \\ \hline \\ \text{motor*} \\ \hline \\ \text{Running time} \\ \hline \\ \text{motor*} \\ \hline \\ \text{spring} \\ \hline \\ \text{Angle of Rotation Adaptation*} \\ \hline \\ \text{Override control*} \\ \hline \\ \text{Override control*} \\ \hline \\ \text{Min. (Min Position) = 0\%} \\ \hline \\ \text{- ZS (Mid. Position) = 100\%} \\ \hline \\ \end{array}$
500 Ω for 4 to 20 mA 1500 Ω for PWM, Floating point and On-Off control Feedback output U* Direction of rotation Mechanical angle of rotation* Running time motor* Spring
1500 Ω for PWM, Floating point and On-Off control
On-Off control Feedback output U* Direction of rotation spring motor Mechanical angle of rotation* Running time motor* Spring 95 sec constant independent of load
Feedback output U* Direction of rotation spring motor Mechanical angle of rotation* Running time motor* Spring spring reversible with CW/CCW mounting reversible with built-in // switch 95° Running time motor* Spring 95 sec constant independent of load 25 sec @-4°F to 122°F [-20°C to 50°C] 60 sec @-22°F [-30°C] Angle of Rotation Adaptation* Override control* Min. (Min Position) = 0% - ZS (Mid. Position) = 50% - Max. (Max. Position) = 100%
Direction of rotation spring motor Mechanical angle of rotation* Running time motor* Spring 95 sec constant independent of load 425 sec @-4°F to 122°F [-20°C to 50°C] 460 sec @-22°F [-30°C] Angle of Rotation Adaptation* Override control* Min. (Min Position) = 0% - ZS (Mid. Position) = 50% - Max. (Max. Position) = 100%
motor reversible with built-in \(\scales \) switch Mechanical angle of rotation* Running time motor* spring
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Running time motor* spring 95 sec constant independent of load (25 sec @-4°F to 122°F [-20°C to 50°C] (60 sec @-22°F [-30°C] Angle of Rotation Adaptation* Off (Default) Off (De
spring <25 sec @-4°F to 122°F [-20°C to 50°C] <60 sec @-22°F [-30°C] Angle of Rotation Adaptation* Off (Default) Override control* Min. (Min Position) = 0% - ZS (Mid. Position) = 50% - Max. (Max. Position) = 100%
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- Max. (Max. Position) = 100%
Position indication visual indicator, 0° to 95°
Humidity 5 to 95% RH, non-condensing
Ambient temperature -22 to 122° F (-30 to 50° C)
Storage temperature -40 to 176° F (-40 to 80° C)
Housing NEMA 2/IP42
Housing material UL 94-5VA
Noise level (max) running <35 dB (A)
spring return <65 dB (A)
Agency listings† cULus acc. to UL60730-1A/-2-14, CAN/CSA
E60730-1, CSA C22.2 No.24-93, CE acc to
89/336/EEC
Quality standard ISO 9001

^{*} Variable when configured with MFT options

[†] Rated impulse voltage 0.8 kV, Control pollution degree 3, Type of action 1.AA.



TF24-MFT US Actuators, Multi-Function Technology



Wiring Diagrams

> INSTALLATION NOTES

1

Provide overload protection and disconnect as required.



CAUTION Equipment damage!

Actuators may be connected in parallel.

Power consumption and input impedance must be observed.

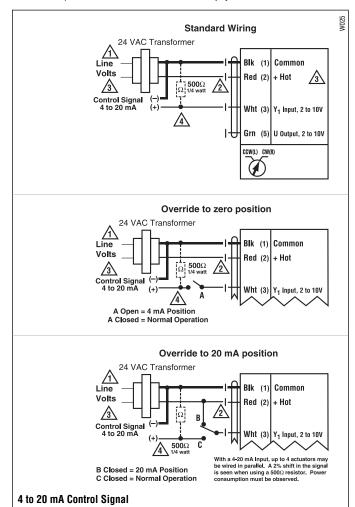
Actuators may also be powered by 24 VDC.



ZG-R01 may be used.

WARNING Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



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